



European Sediment Network

 POLITECNICO DI MILANO



An hydraulic monitoring system on a Bridge over river Po

8th International SedNet conference, 6-9 November 2013, Lisbon (Portugal)

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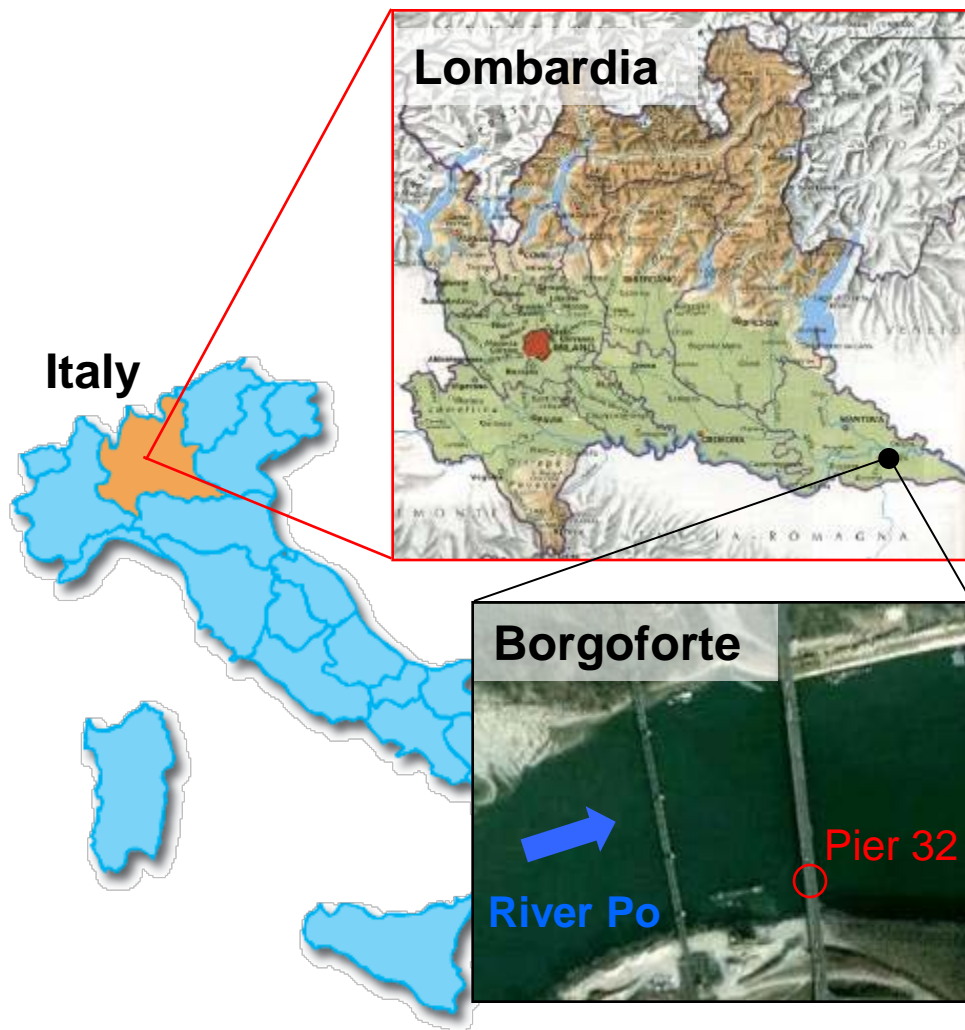


The Monitoring system location



European Sediment Network

Monitoring system is working from March 2011





The Monitoring system location



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Monitoring system is working from March 2011

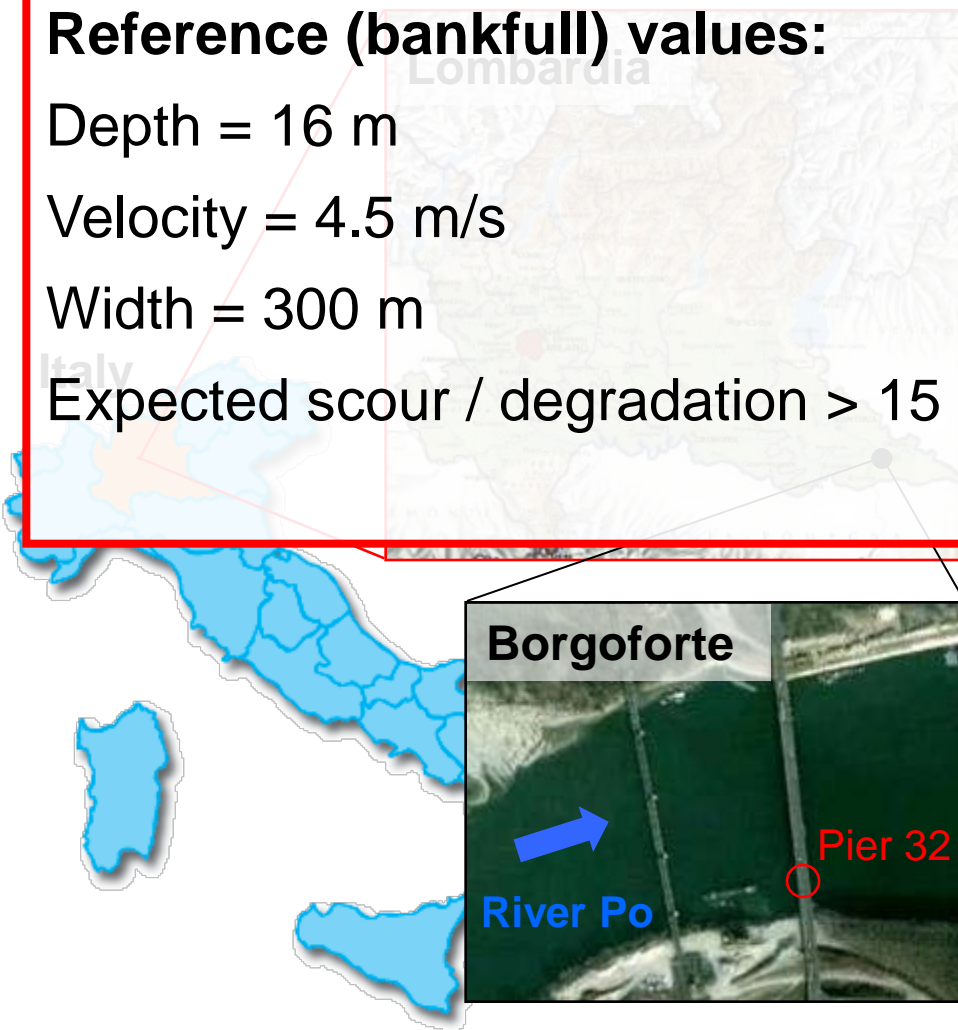
Reference (bankfull) values:

Depth = 16 m

Velocity = 4.5 m/s

Width = 300 m

Expected scour / degradation > 15 m





Goals of the project



European Sediment Network

1) Define the Bridge loads

- *Wind drag force*
- *Water drag force*
- *Traffic forces*

2) Define others additional phenomena

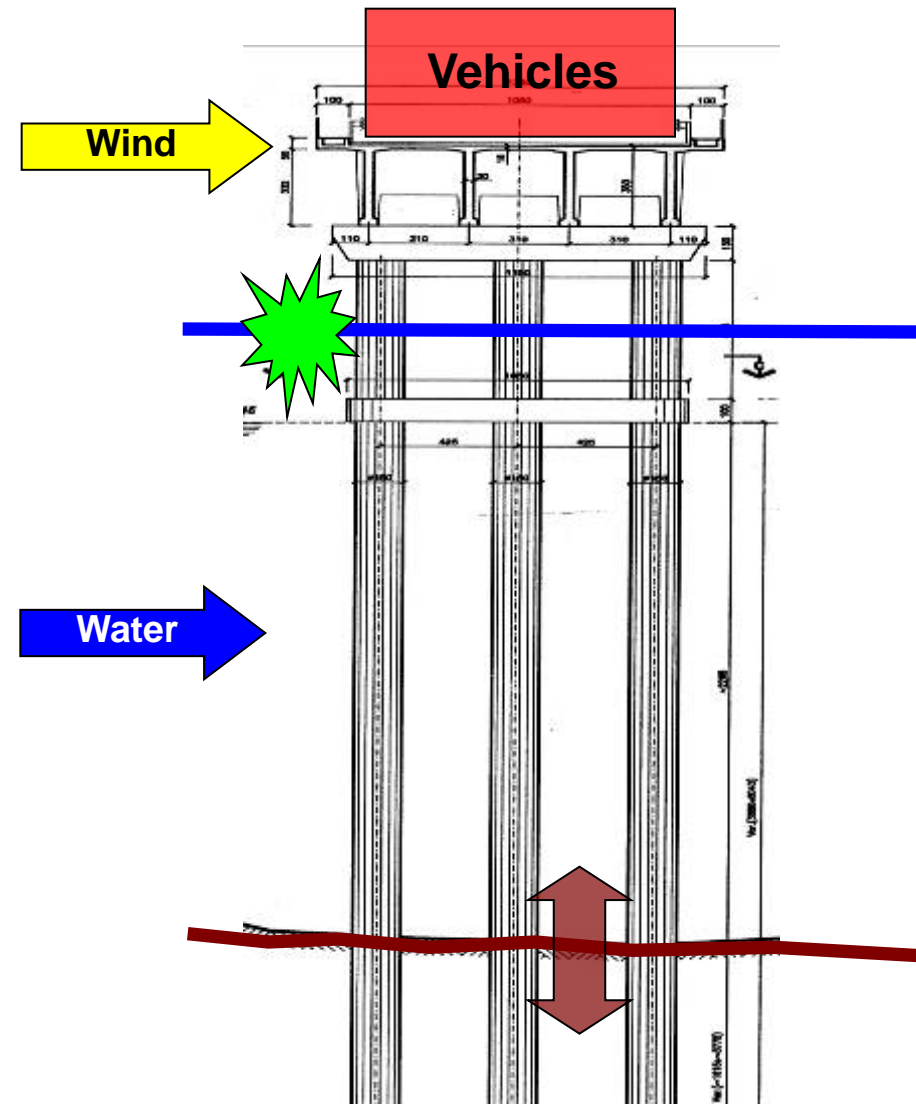
- *Scour around pier*
- *Trapped debris upstream the pier*

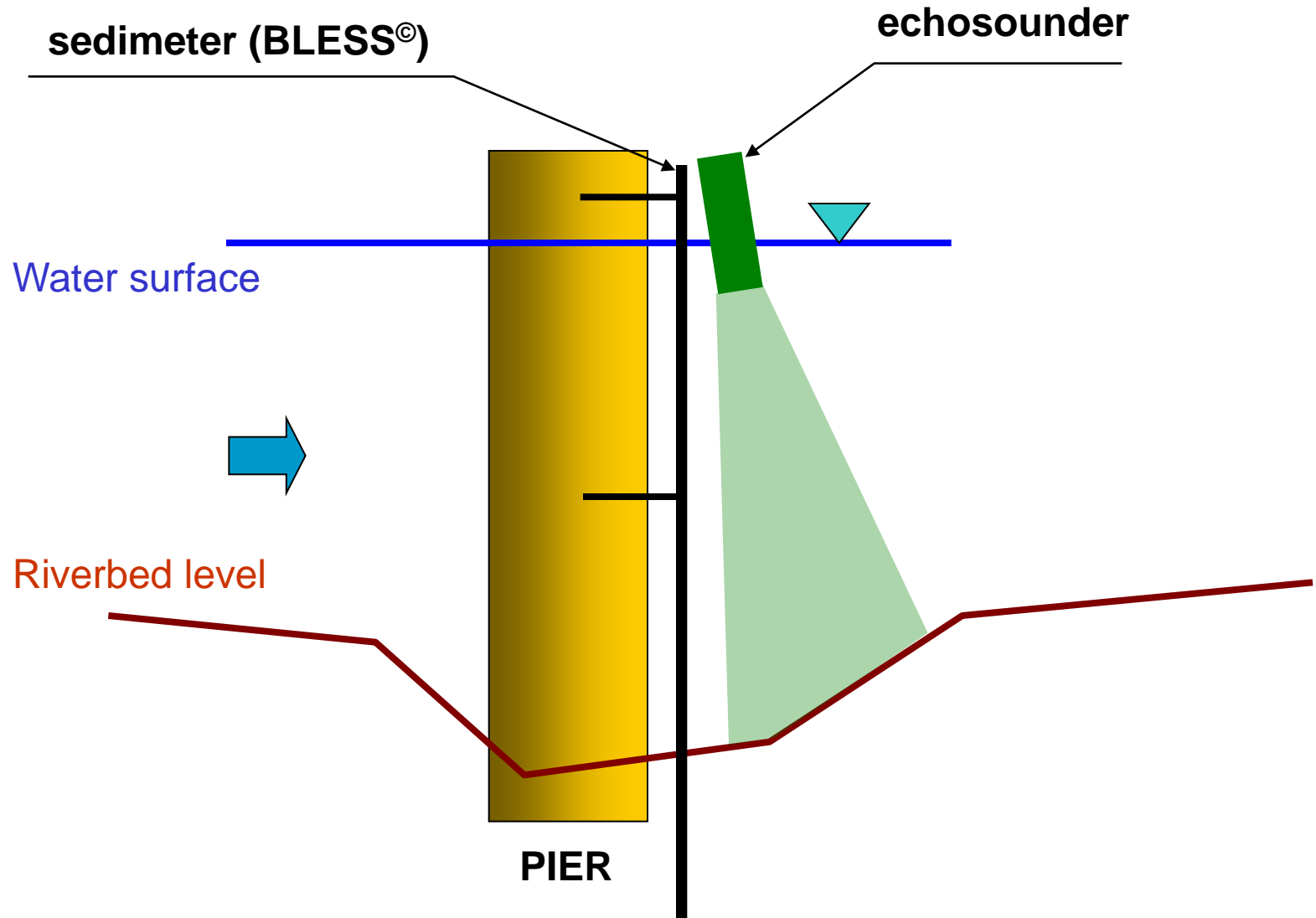
3) Define monitoring system configuration

4) Define structural model of the pier

5) Evaluate the safety factor of the pier

6) Define the management plans



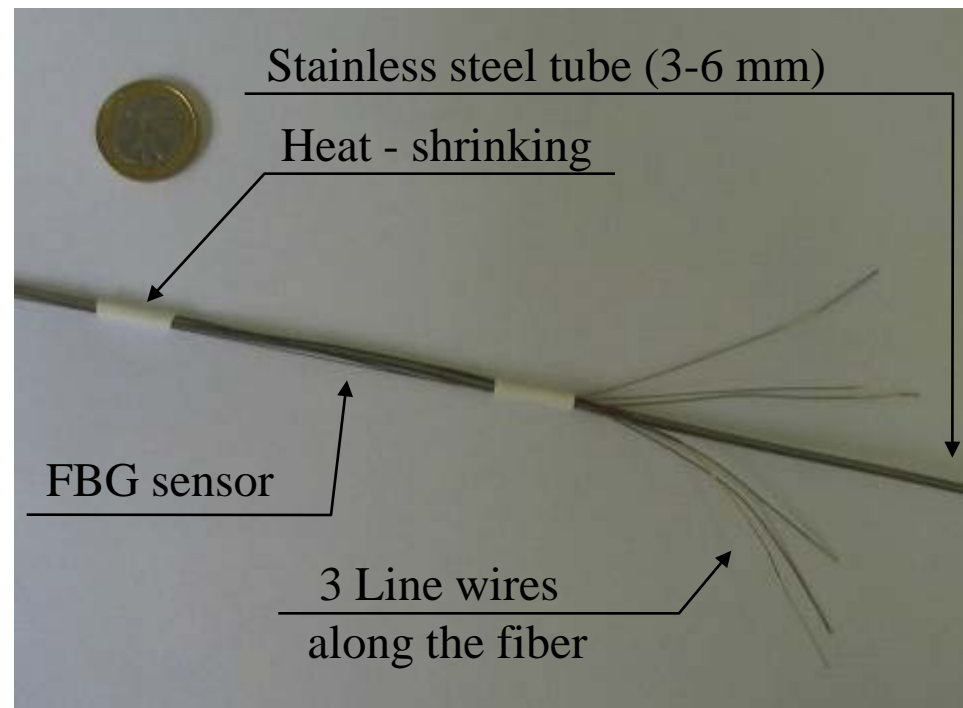
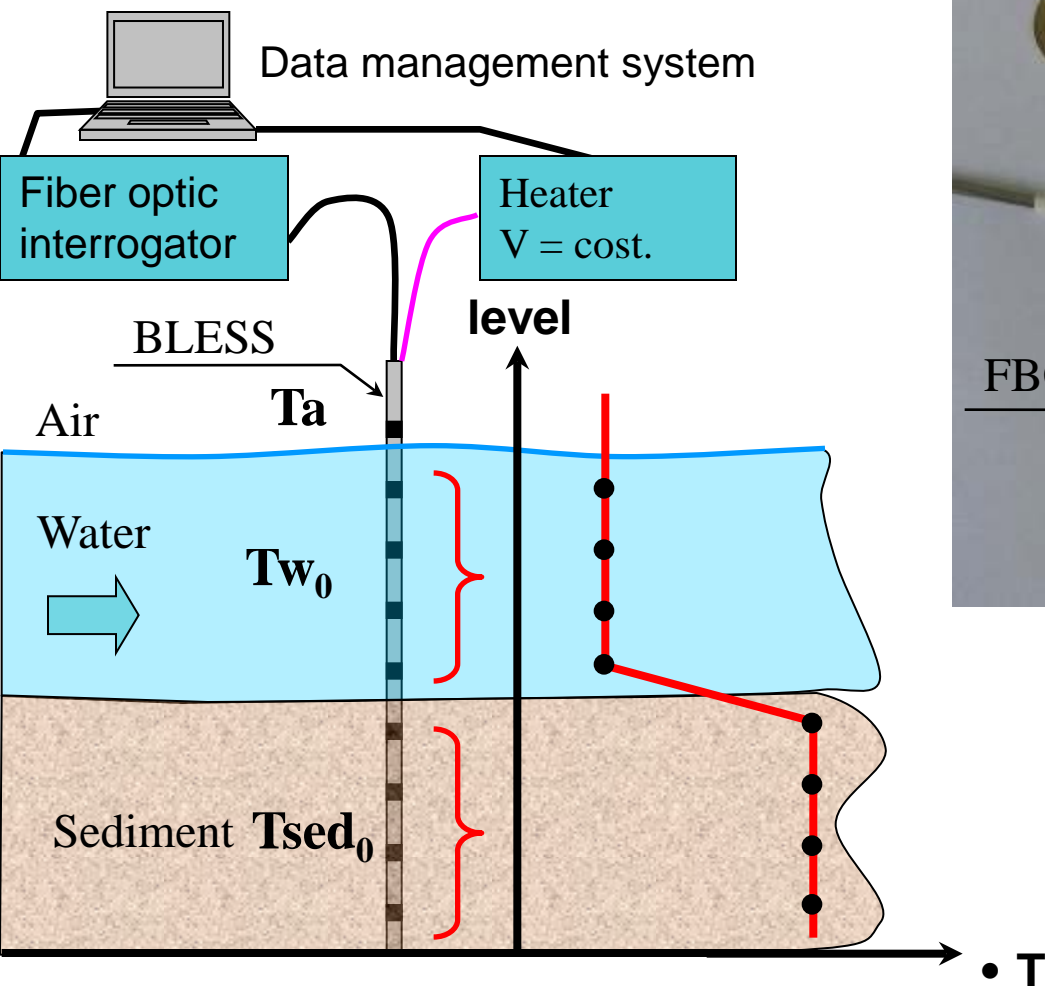


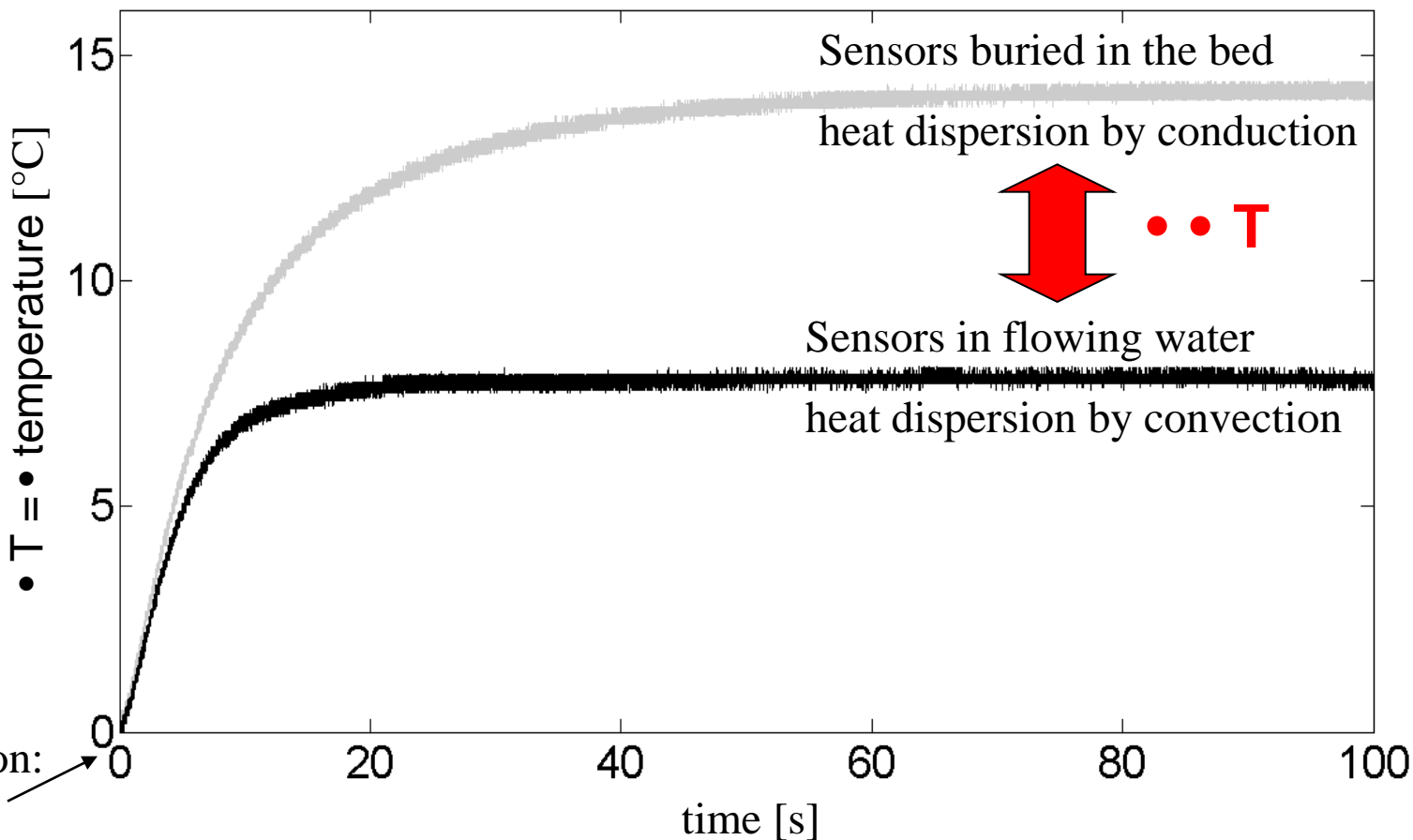


BLESS[®] → How does it works?



example layout of the monitoring system

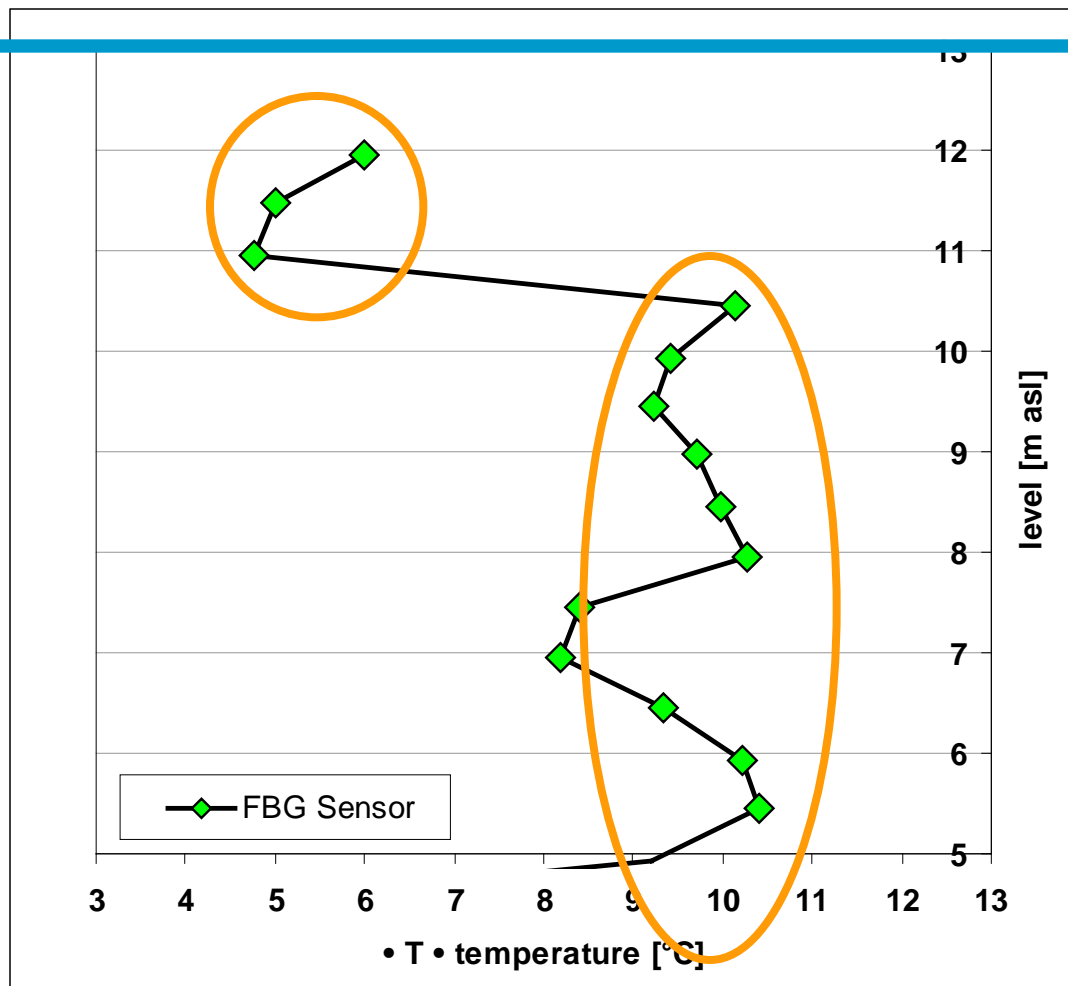
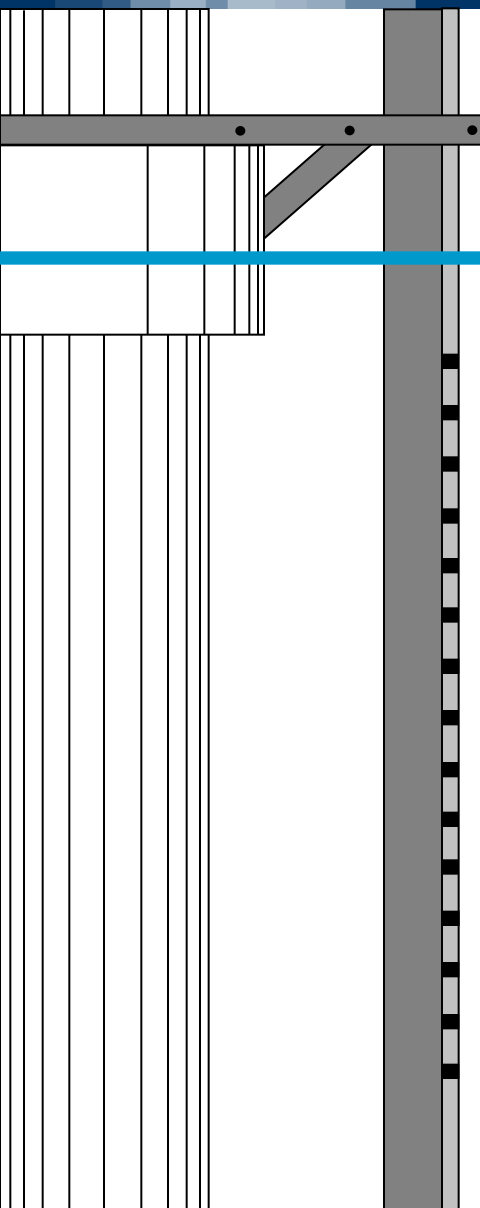




Laboratory results



BLESS[®] → Sensor response

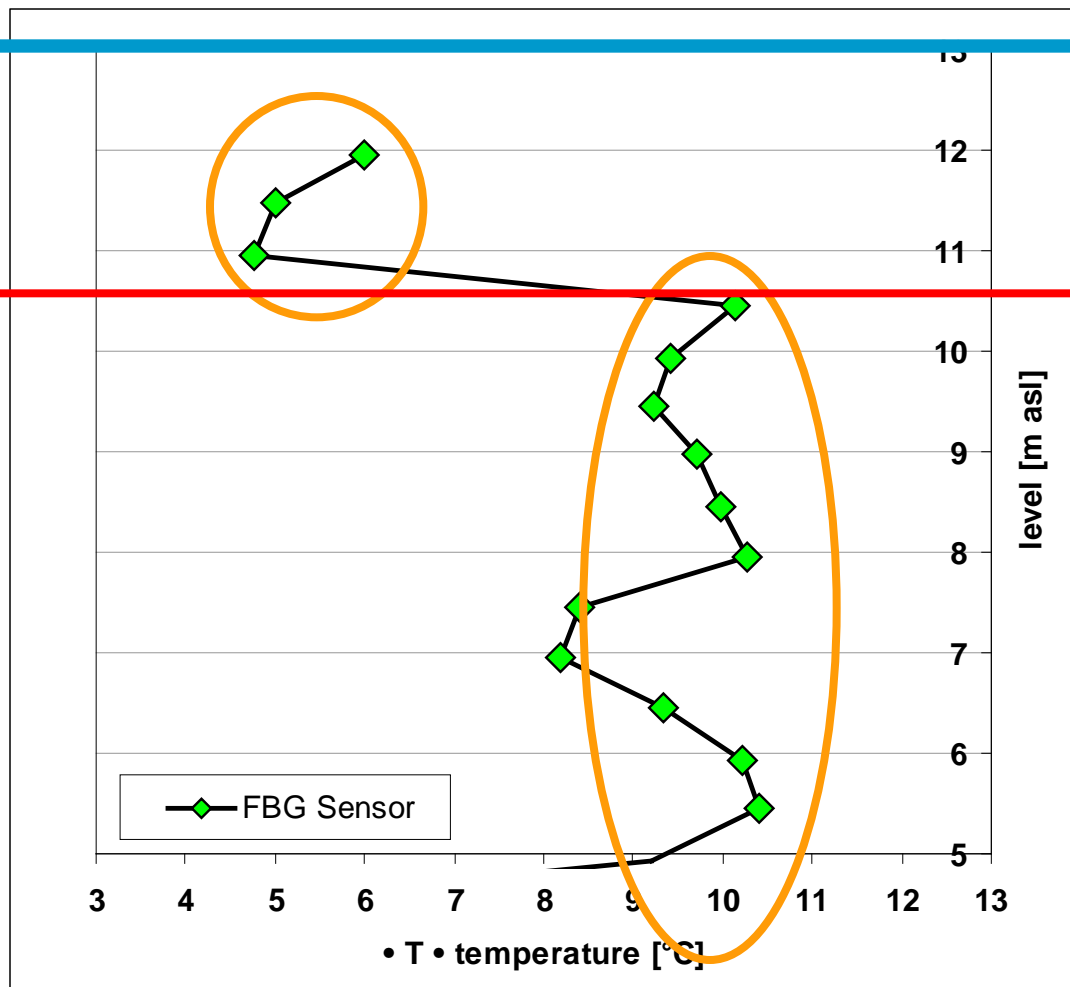




BLESS[®] → Sensor response

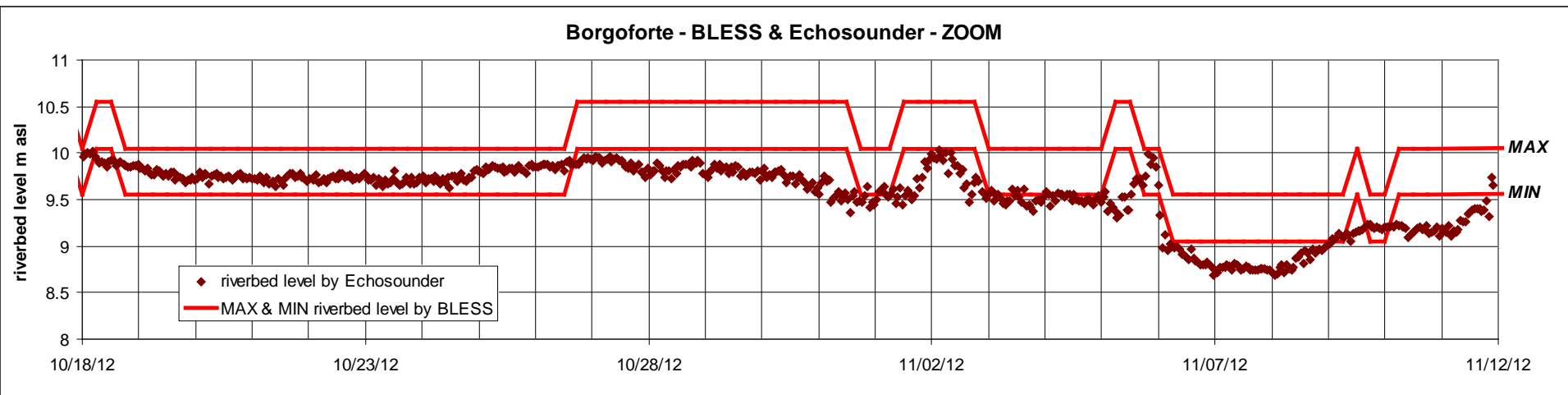


Echo-sounder





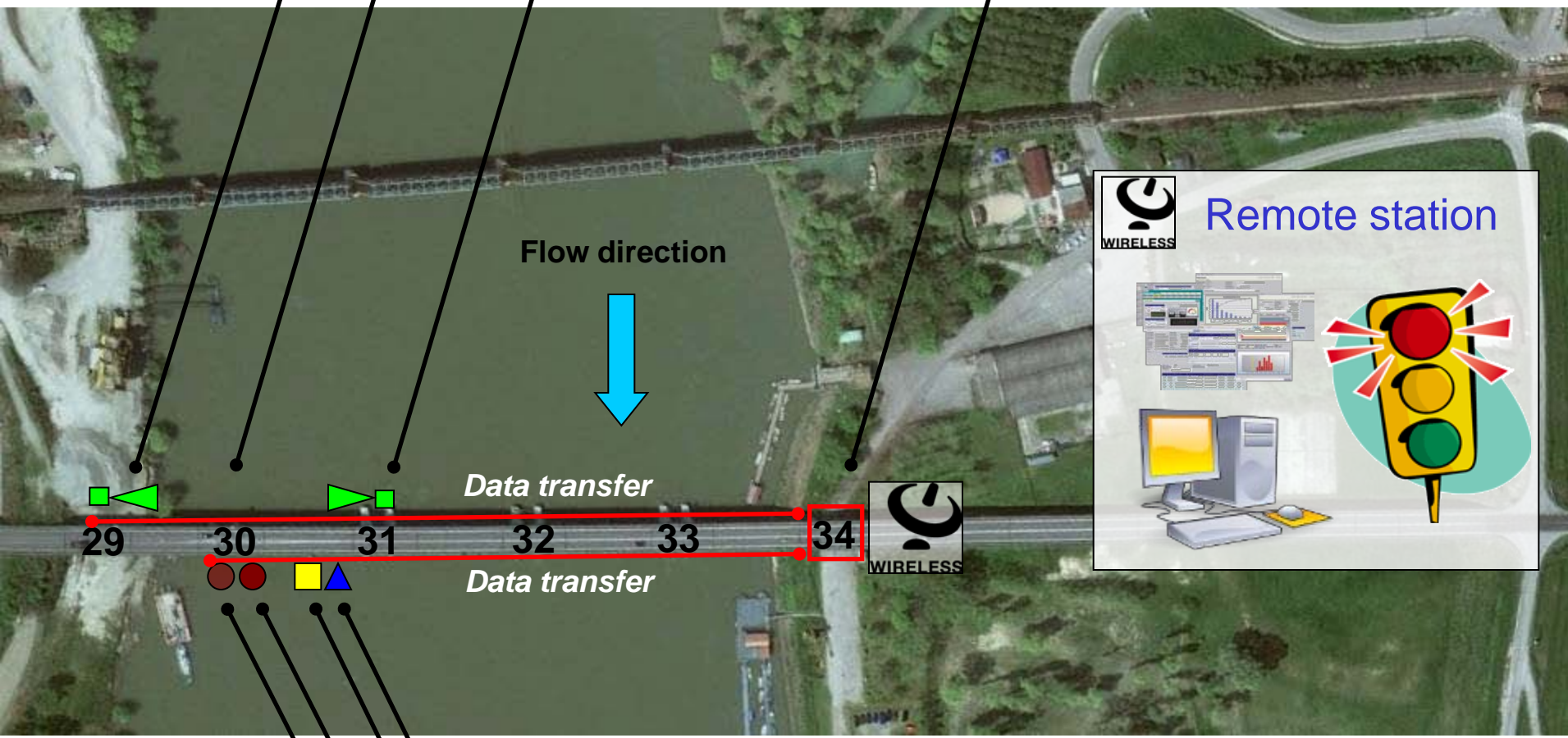
BLESS[®] vs Echo-sounders



The Monitoring system configuration



Video camera Infrared Video camera Control room



Echo-sounder
BLESS sedimenter

Hydrometer
Anemometer



From monitoring to safety factor



Monitoring



Loads

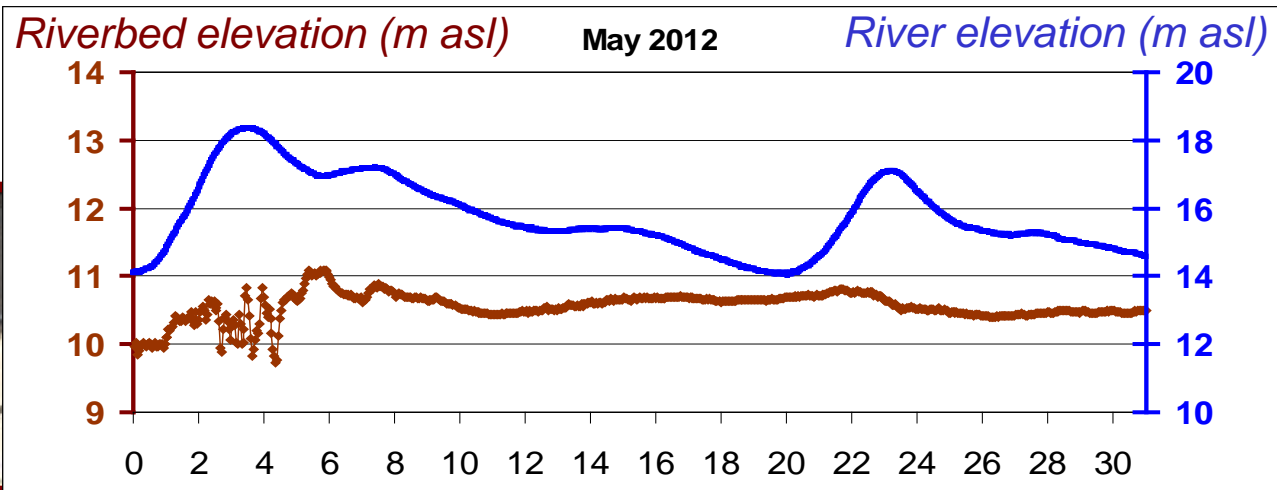


Structure

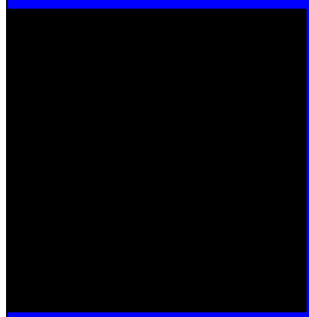


Safety factor

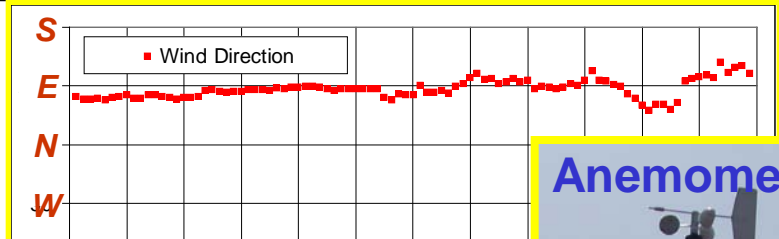
Echo-sounder



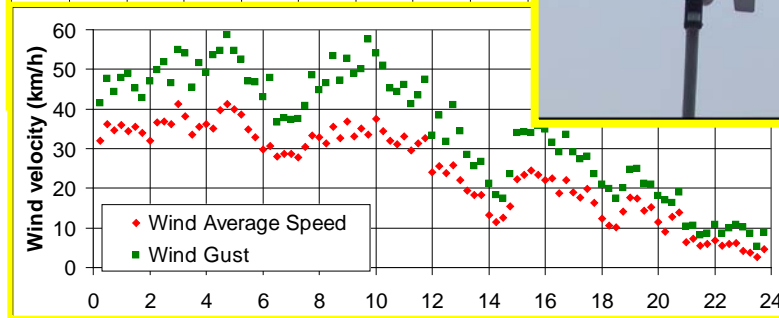
Hydrometer



Video camera

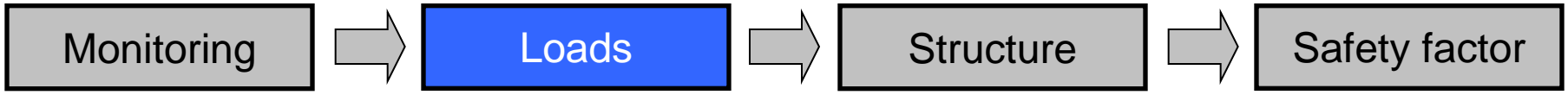


Anemometer





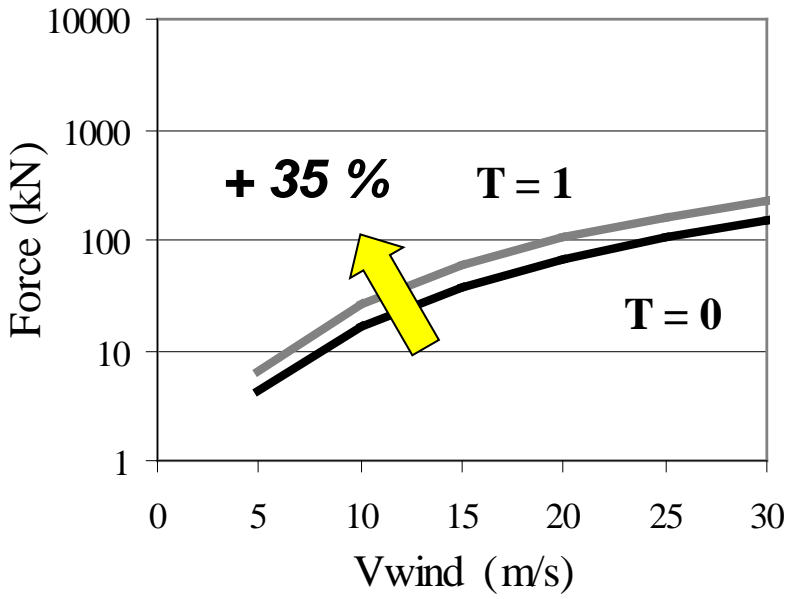
From monitoring to safety factor



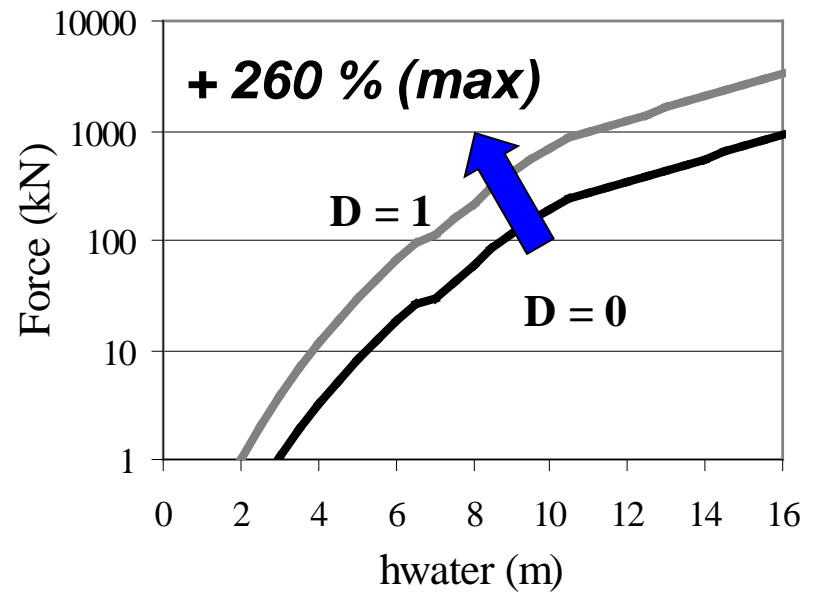
Wind $\rightarrow F_w = f(V_w, T)$

Water $\rightarrow F_{wa} = f(h_{wa}, D)$

Wind drag force (pier 30) (a)

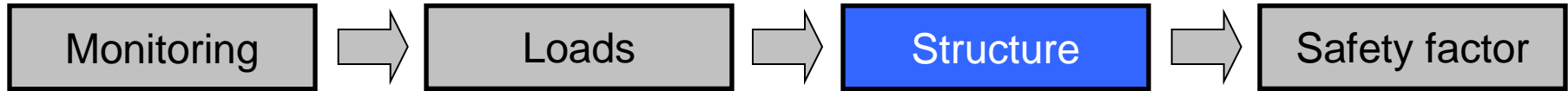


Water drag force (pier 30) (b)





From monitoring to safety factor

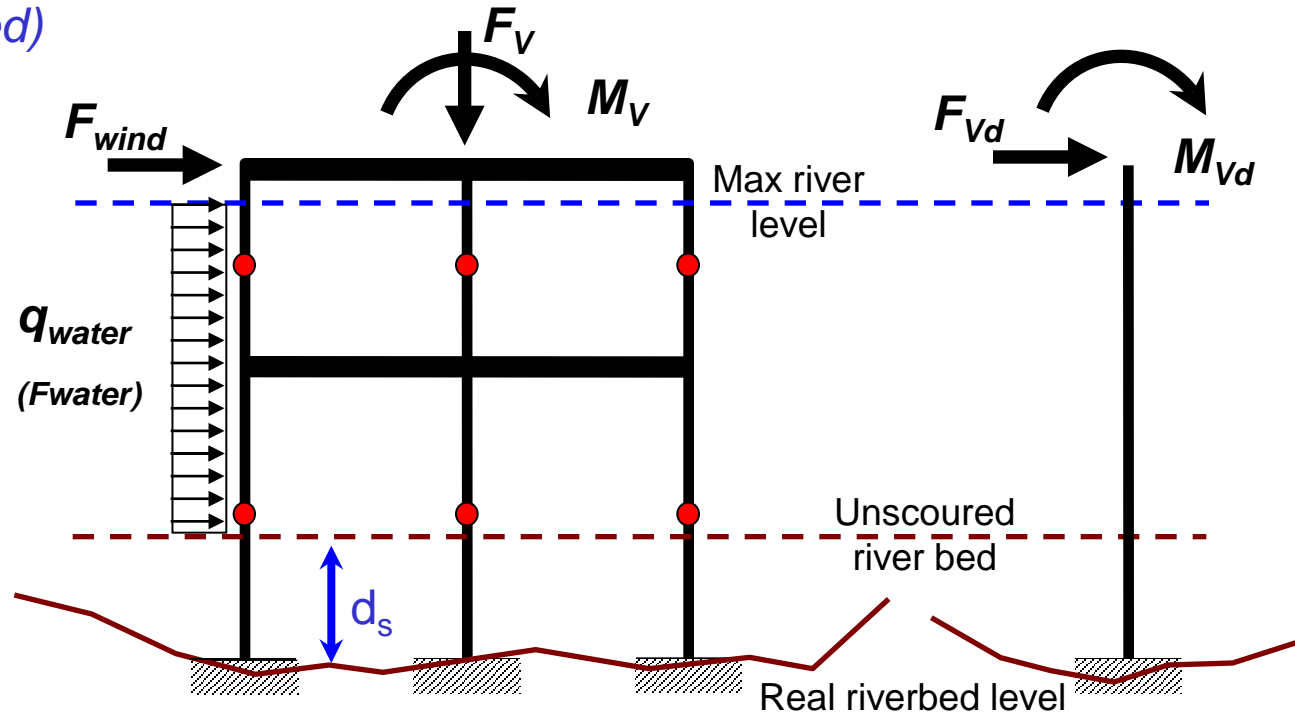


Wind $\rightarrow F_w = f(V_w, T)$

Water $\rightarrow F_{wa} = f(h_{wa}, D)$

(Pier weight is also included)

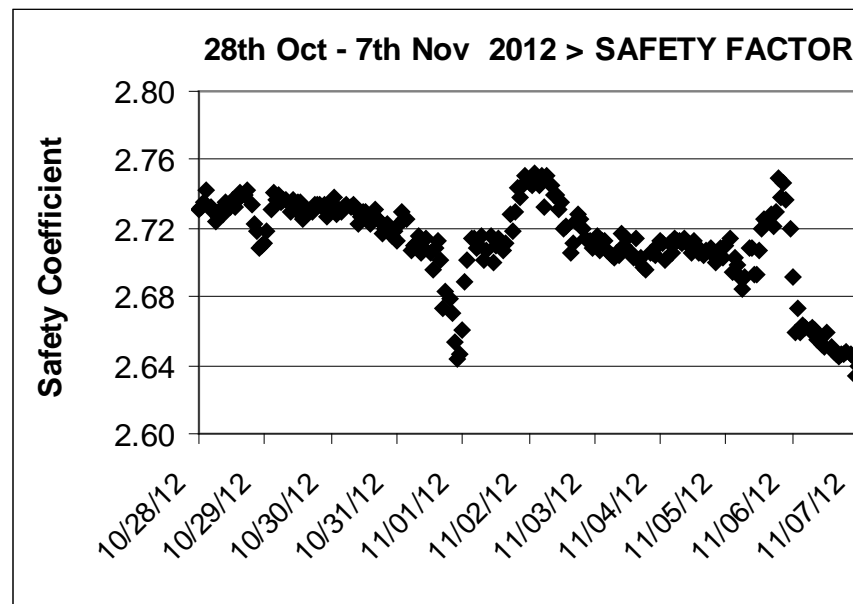
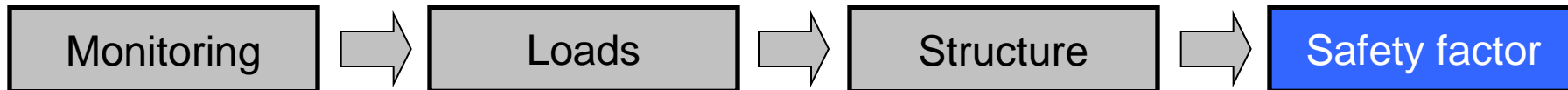
Vehicles {
 Weight $\rightarrow F_V = f(T), M_V = f(T)$
 Deceleration $\rightarrow F_{Vd} = f(T), M_{Vd} = f(T)$



Total actions = $f(V_w, h_{wa}, d_s, T, D)$



From monitoring to safety factor





GLOBAL TARGET: ACHIEVED (system works!)

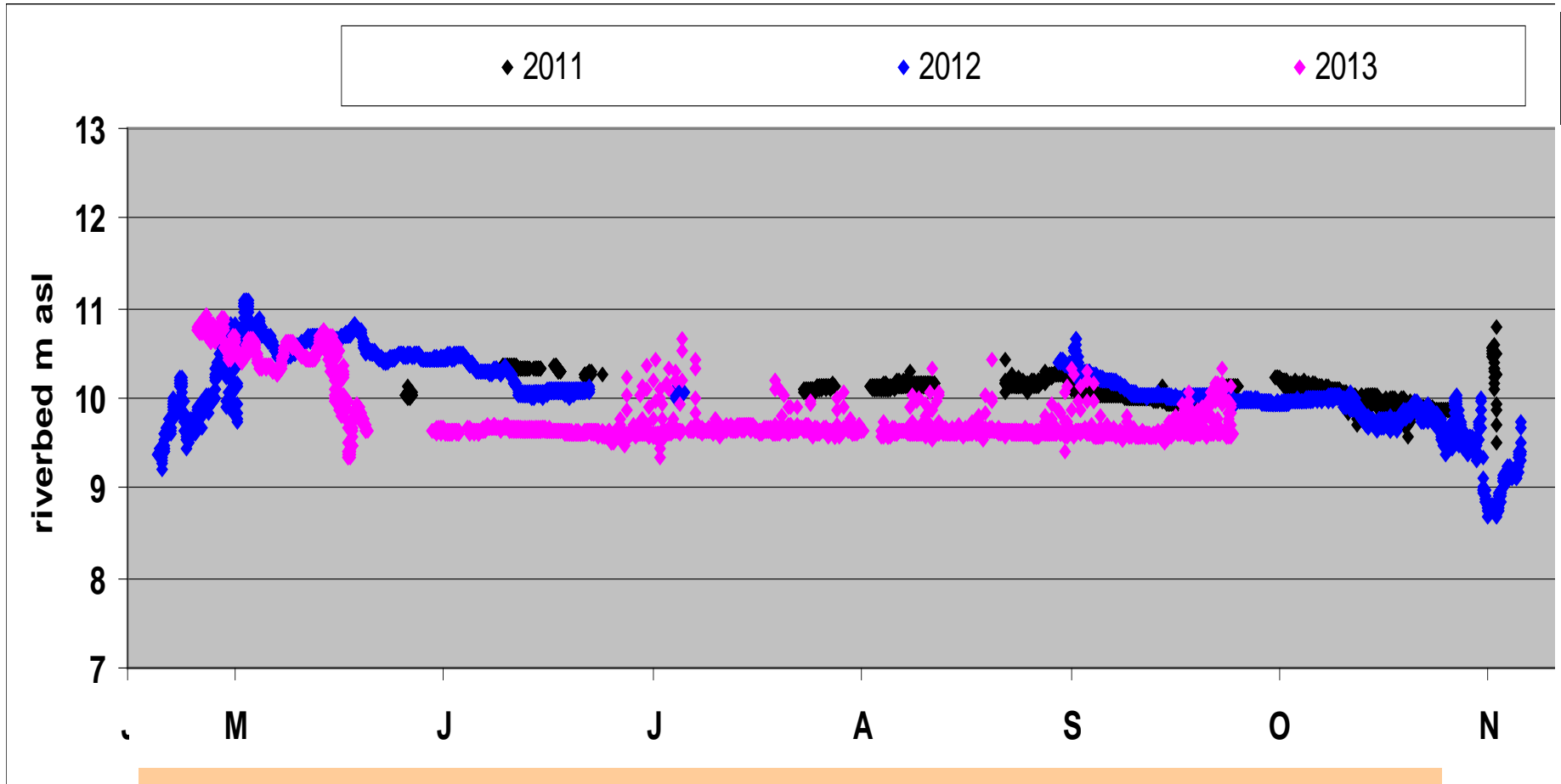
CRITICALITIES: BED LEVEL

- we cannot robustly forecast it
- measurements not standard

ONGOING VALIDATION



From 2011 to 2013: bed level



ONGOING VALIDATION



... conclusions and next steps



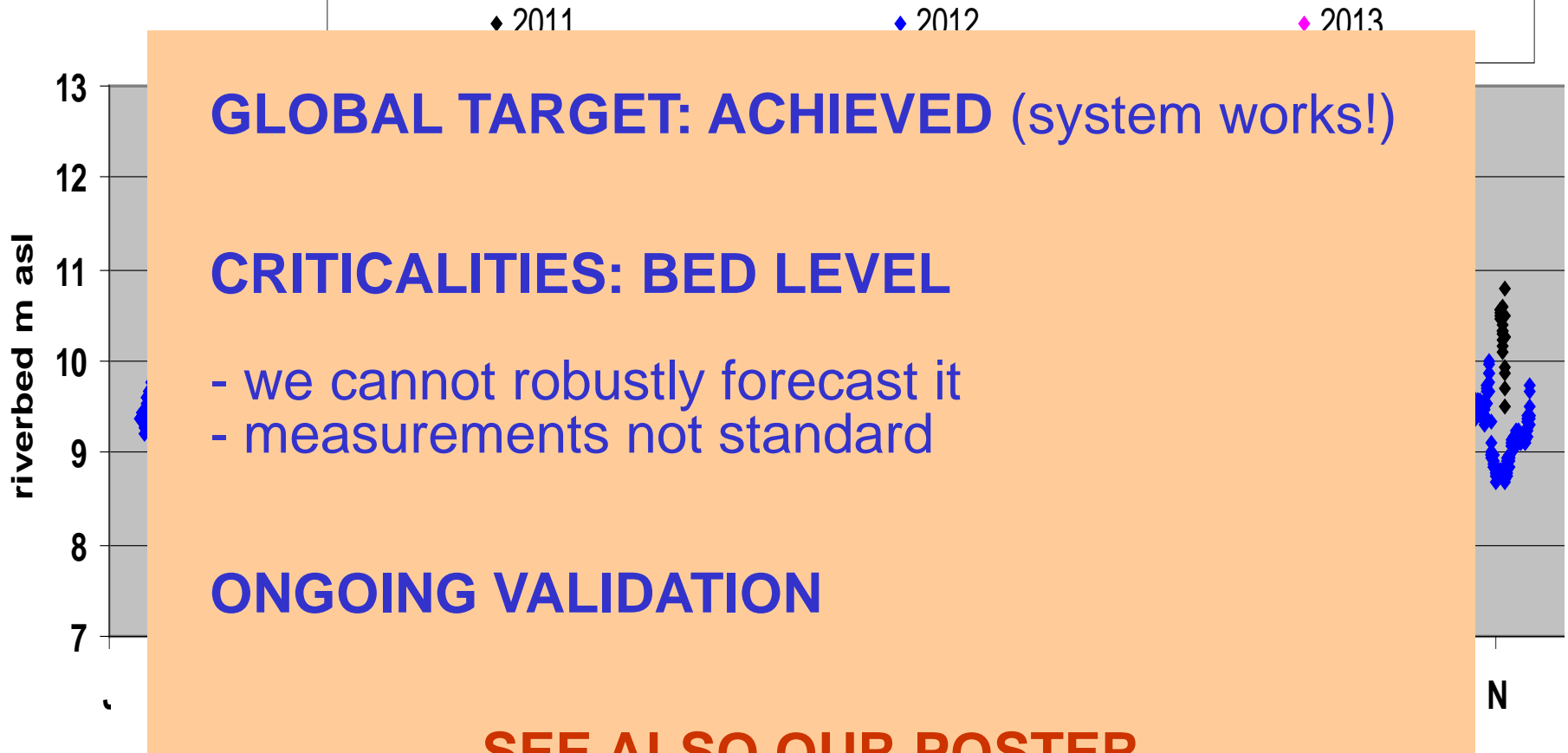
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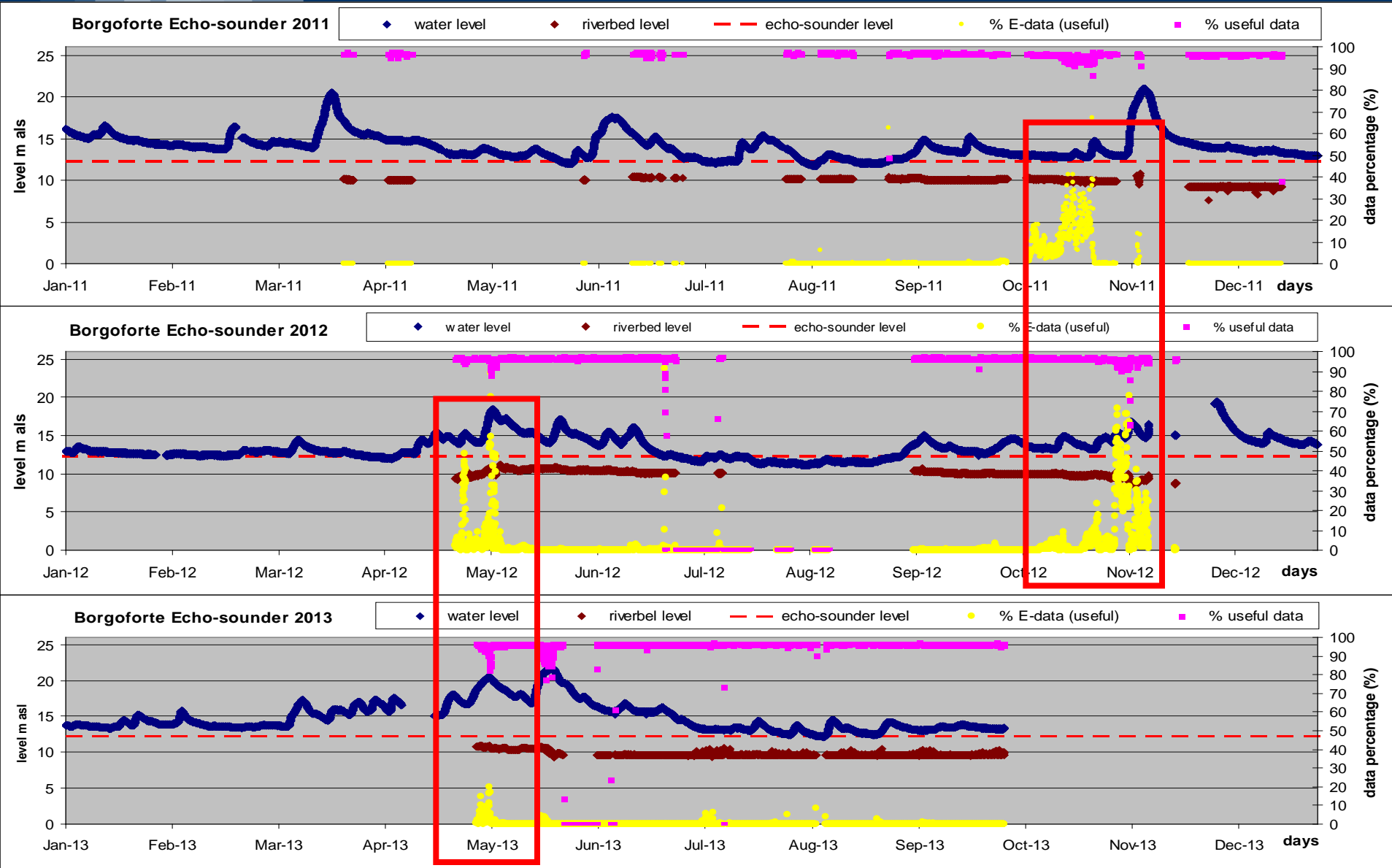
ONGOING VALIDATION

SEE ALSO OUR POSTER



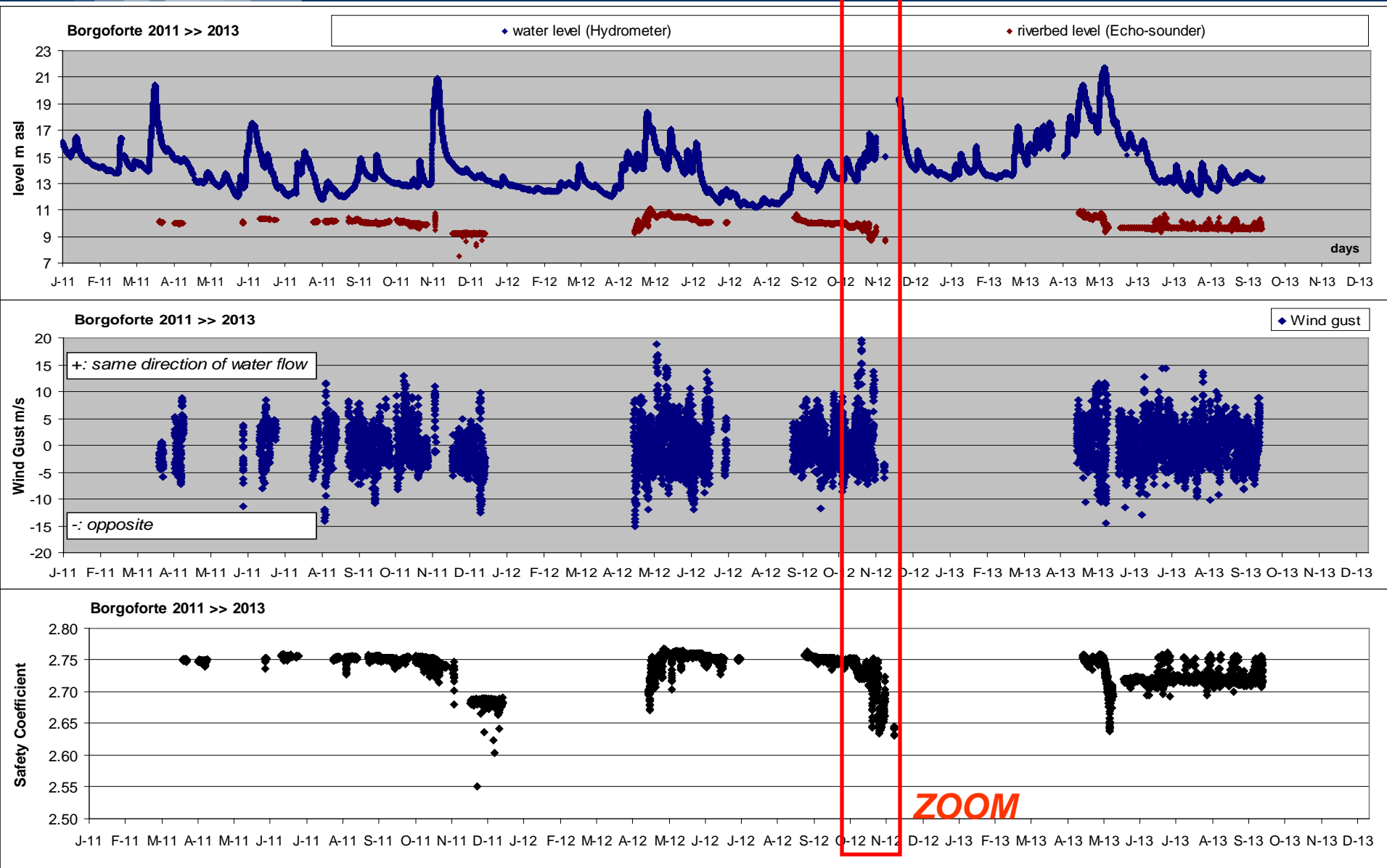


From 2011 to 2013: focus on Echo-sounder





From 2011 to 2013: parameters → safety factor





From 2011 to 2013: parameters → safety factor

